IMS Series

High-Performance Long-Travel Linear Stages

Newport®
Experience | Solutions

USER'S MANUAL

Precision Motion – *Guaranteed*™

Warranty

Newport Corporation warrants this product to be free from defects in material and workmanship for a period of 1 year from the date of shipment. If found to be defective during the warranty period, the product will either be repaired or replaced at Newport's discretion.

To exercise this warranty, write or call your local Newport representative, or contact Newport headquarters in Irvine, California. You will be given prompt assistance and return instructions. Send the instrument, transportation prepaid, to the indicated service facility. Repairs will be made and the instrument returned, transportation prepaid. Repaired products are warranted for the balance of the original warranty period, or at least 90 days.

Limitation of Warranty

This warranty does not apply to defects resulting from modification or misuse of any product or part.

CAUTION

Warranty does not apply to damages resulting from:

- **Incorrect usage:**
  - **Load on the stage greater than maximum specified load.**
  - **Carriage speed higher than specified speed.**
  - **Improper grounding.**
    - ¬ **Connectors must be properly secured.**
    - ¬ **When the load on the stage represents an electrical risk, it must be connected to ground.**
  - **Excessive or improper cantilever loads.**
- **Modification of the stage or any part thereof.**

CAUTION

Please return equipment in the original (or equivalent) packing.

You will be responsible for damage incurred from inadequate packaging if the original packaging is not used.

This warranty is in lieu of all other warranties, expressed or implied, including any implied warranty of merchantability or fitness for a particular use. Newport Corporation shall not be liable for any indirect, special, or consequential damages.

No part of this manual may be reproduced or copied without the prior written approval of Newport Corporation.

This manual has been provided for information only and product specifications are subject to change without notice. Any changes will be reflected in future printings.

Table of Contents

Warranty ii
EC Declaration of Conformity v
Definitions and Symbols vi
Warnings vii
Cautions viii

1.0 — Introduction 1

2.0 — Description 2
2.1 Design Details 2

3.0 — Characteristics 3
3.1 Definitions 3
3.2 Mechanical Specifications 4
3.3 Load Specification Definitions 4
3.4 Load Characteristics and Stiffness 5
3.5 Stage Weights 5

4.0 — Drive 6
4.1 Stepper Drive Version 6
4.2 DC-Servo Drive Versions 6

5.0 — Motor 7
5.1 UE56UP Motor Characteristics 7
5.2 Command Signals for the Stepper Motor 7
5.3 UE511S2 Motor Characteristics 7
5.4 Command Signals for the DC-Motor 7
5.5 Sensor Position 8
5.6 Feedback Signal Position 8
5.7 Pinouts 9

6.0 — Connection to Newport Controllers 10
6.1 Warnings on Controllers 10
6.2 Connection 11
6.3 Cables 11
6.4 MMCABLE-3 Cable 11
6.5 MCAB-3 Cable 12

7.0 — Connection to Non-Newport Electronics 13
7.1 Connections 13

8.0 — Dimensions 14
8.1 (M-)IMS Stages 14
8.2 (M-)IMS Stages Top Plate Interface 15
8.3 (M-)IMS Stages without Top Plate Interface 15

9.0 — XY Assemblies 16

10.0 — Accessory: EQ180 Bracket 17

11.0 — Maintenance 18
11.1 Maintenance 18
11.2 Repair 18
11.3 Calibration 18

Service Form 19

EC Declaration of Conformity

IMS Series

Newport
Experience | Solutions

EC Declaration of Conformity

following Annex II-1A
of Directive 2006/42/EC on machinery

The manufacturer:

MICRO-CONTROLE Spectra-Physics,
9, rue du bois sauvage
F-91055 Evry FRANCE

Hereby declares that the machinery:

- Description: " IMS "
- Function: High-Performance Translation stages
- Models: M-/IMS300/CC/CCHA/PP, M-/IMS400/CC/CCHA/PP, M-/IMS500/CC/CCHA/PP, M-/IMS600/CC/CCHA/PP

– the technical file of which was compiled by:

Mr Dominique DEVIDAL, Quality Director,
MICRO-CONTROLE Spectra-Physics, Zone Industrielle - B.P.29
F-45340 Beaune La Rolande France

– complies with all the relevant provisions of the Directive 2006/42/EC on machinery.
– complies with all the relevant provisions of the Directive 2004/108/EC relating to electro-magnetic compatibility.

– was designed and built in accordance with the following harmonised standards:

- NF EN 61326-1:2013 « Electrical equipment for measurement, control and laboratory use – EMC requirements – Part 1: General requirements »
- NF EN 55011:2010/A1:2011 Class A

– was designed and built in accordance with the following other standards:

- NF EN 61000-4-2
- NF EN 61000-4-3
- NF EN 61000-4-4
- NF EN 61000-4-5
- NF EN 61000-4-6

ORIGINAL DECLARATION

Done in Beaune La Rolande on 26 February 2015
Dominique DEVIDAL
Quality Director

DC1-EN rev:A

Definitions and Symbols

The following terms and symbols are used in this documentation and also appear on the product where safety-related issues occur.

General Warning or Caution

The exclamation symbol may appear in warning and caution tables in this document. This symbol designates an area where personal injury or damage to the equipment is possible.

The following are definitions of the Warnings, Cautions and Notes that may be used in this manual to call attention to important information regarding personal safety, safety and preservation of the equipment, or important tips.

WARNING

Warning indicates a potentially dangerous situation which can result in bodily harm or death.

CAUTION

Caution indicates a potentially hazardous situation which can result in damage to product or equipment.

NOTE

Note indicates additional information that must be considered by the user or operator.

European Union CE Mark

The presence of the CE Mark on Newport Corporation equipment means that it has been designed, tested and certified as complying with all applicable European Union (CE) regulations and recommendations.

Warnings and Cautions

ATTENTION

This stage is a Class A device. In a residential environment, this device can cause electromagnetic interference. In this case, suitable measures must be taken by the user.

Warnings

WARNING

The motion of objects of all types carries potential risks for operators. Ensure the protection of operators by prohibiting access to the dangerous area and by informing the personnel of the potential risks involved.

WARNING

Do not use this stage when its motor is emitting smoke or is unusually hot to the touch or is emitting any unusual odor or noise or is in any other abnormal state.

Stop using the stage immediately, switch off the motor power and then disconnect the electronics power supply.

After checking that smoke is no longer being emitted contact your Newport service facility and request repairs. Never attempt to repair the stage yourself as this can be dangerous.

WARNING

Make sure that this stage is not exposed to moisture and that liquid does not get into the stage.

Nevertheless, if any liquid has entered the stage, switch off the motor power and then disconnect the electronics from power supply.

Contact your Newport service facility and request repairs.

WARNING

Do not insert or drop objects into this stage, this may cause an electric shock, or lock the drive.

Do not use this stage if any foreign objects have entered the stage. Switch off the motor power and then disconnect the electronics power supply.

Contact your Newport service facility for repairs.

WARNING

Do not place this stage in unstable locations such as on a wobbly table or sloping surface, where it may fall or tip over and cause injury.

If this stage has been dropped or the case has been damaged, switch off the motor power and then disconnect the electronics power supply.

Contact your Newport service facility and request repairs.

WARNING

Do not attempt to modify this stage; this may cause an electric shock or downgrade its performance.

WARNING

Do not exceed the usable depth indicated on the mounting holes (see section “Dimensions”). Longer screws can damage the mechanics or cause a short-circuit.

Cautions

CAUTION

Do not place this stage in a hostile environment such as X-Rays, hard UV,… or in any vacuum environment.

CAUTION

Do not place this stage in a location affected by dust, oil fumes, steam or high humidity. This may cause an electric shock.

CAUTION

Do not leave this stage in places subject to extremely high temperatures or low temperatures. This may cause an electric shock.

- **Operating temperature: +10 to +35 °C**
- **Storage temperature: -10 to +40 °C (in its original packaging)**

CAUTION

Do not move this stage if its motor power is on.

Make sure that the cable to the electronics is disconnected before moving the stage. Failure to do so may damage the cable and cause an electrical shock.

CAUTION

Be careful that the stage is not bumped when it is being carried. This may cause it to malfunction.

CAUTION

When handling this stage, always unplug the equipment from the power source for safety.

CAUTION

When the carriage is in its end-of-run position, it is strongly recommended not to go beyond this point as this may damage the stage mechanism.

CAUTION

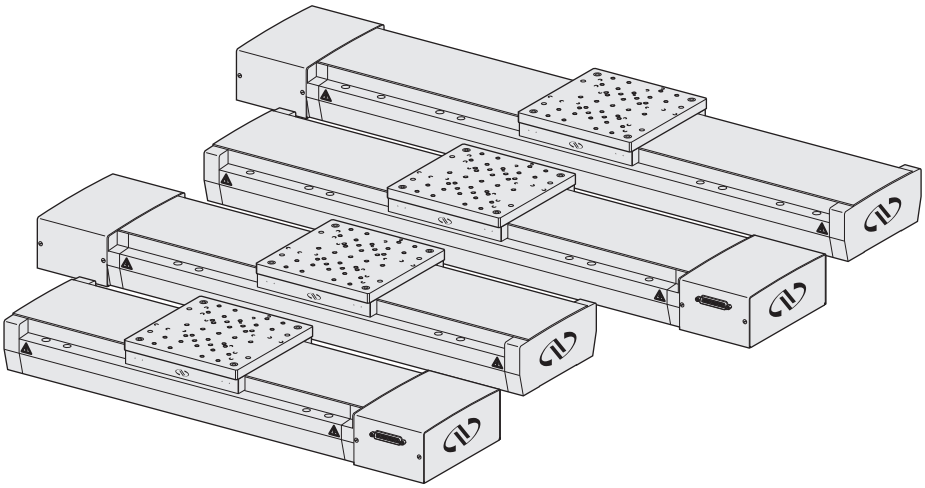
Contact your Newport service facility to request cleaning and specification control every year.

High-Performance Long-Travel Linear Stages IMS Series

1.0 Introduction

This manual provides operating instructions for the stage that you have purchased in the IMS Series:

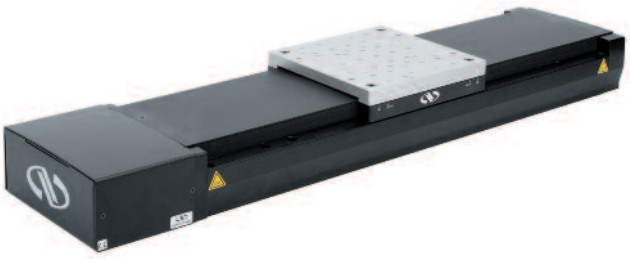
- (M-)IMS-PP
- (M-)IMS-CC
- (M-)IMS-CCHA



IMS Series linear stages: 300, 400, 500 and 600 mm travel ranges.

RECOMMENDATION

We recommend you read carefully the chapter "Connection to electronics" before using the IMS stage.



(M-)IMS400 translation stage.

2.0 Description

Two (M-)IMS stages and one EQ180 bracket in an XZ configuration.

The IMS Series linear stage complements the (M-)ILS Series by providing longer linear travel ranging from 300–600 mm. The stages feature robust designs with high performance but without high cost, making them cost-effective solutions for precision industrial and laboratory applications.

Using the same industry-proofed technology as the ILS Series, the IMS Series features a FEM optimized, aluminum extruded body that is highly stiff, while minimizing the bending effect caused by different thermal expansion coefficients of the aluminum body and the steel rails.

Smooth running recirculating ball bearing slides with ball separators provide accurate linear motion and avoid ball cage migration found on linear ball bearings or crossed roller bearings.

A highly-stiff, backlash-free, 5 mm pitch ball screw ensures rapid movements with fast step and settling times, while minimizing heating and extending the lifetime of the stage.

Position measurements are read on a 4000 pts/rev. rotary encoder, mounted directly on the ball screw to avoid screw/coupling errors. For more demanding precision positioning requirements, the IMS Series is available with a highly interpolated linear scale providing 0.1 µm resolution feedback.

The completely closed design of the IMS Series with an upper rigid cover prevents damage to the drive train, underlining its robustness and long lasting values. (M-)IMS stages also feature a motor side mounted origin for repeatable initialization, limit switches to prevent over travel, and elastomeric end-of-run dampers for smooth emergency braking.

For optimal performance, we recommend the use of our motion controllers.

The IMS Series stages are supplied with a 5-meter cable for connection to our motion controllers.

2.1 Design Details

Base Material	Extruded Aluminum
Bearings	Double-row recirculating ball bearings with caged balls
Drive Mechanism	Backlash-free ball screw
Drive Screw Pitch (mm)	5
Feedback	CC, PP: Screw mounted rotary encoder, 4,000 pts/rev, index pulse CCHA: Linear steel scale, 20 µm signal period, 0.1 µm resolution
Limit Switches	Optical
Origin	Optical, approx. 8 mm from motor side limit
Motor	CC, CCHA: DC servo motor UE511S2 PP: 2-phase stepper motor UE56UP, 1 Full-Step = 20 Encoder pulses; In order to close the loop on the encoder, it is needed to drive these motors in micro-step modus with at least 20 micro-steps per full-step.
Cable	5 m long motor cable included

RoHS Compliant

NOTE

This product complies with the RoHS directive (Restriction of Hazardous Substances).

3.0 Characteristics

3.1 Definitions

Specifications of our products are established in reference to ISO 230 standard part II “Determination of accuracy and repeatability of positioning numerically controlled axes”.

This standard gives the definition of position uncertainty which depends on the 3 following parameters:

(Absolute) Accuracy

Difference between ideal position and real position.

On-Axis Accuracy

Difference between ideal position and real position after the compensation of linear errors.

Linear errors include: cosine errors, inaccuracy of screw or linear scale pitch, angular deviation at the measuring point (Abbe error) and thermal expansion effects. All Newport motion electronics can compensate for linear errors.

The relation between absolute accuracy and on-axis accuracy is as follows:

$$Absolute\ Accuracy = On\text{-}Axis\ Accuracy + Correction\ Factor_{x}\ Travel$$

Repeatability

Ability of a system to achieve a commanded position over many attempts.

Reversal Value (Hysteresis)

Difference between actual position values obtained for a given target position when approached from opposite directions.

Minimum Incremental Motion (MIM or Sensitivity)

The smallest increment of motion a device is capable of delivering consistently and reliably.

Resolution

The smallest increment that a motion device can theoretically move and/or detect. Resolution is not achievable, whereas MIM, is the real output of a motion system.

Yaw, Pitch

Rotation of carriage around the Z axis (Yaw) or Y axis (Pitch), when it moves.

The testing of on-axis accuracy, repeatability, and reversal error are made systematically with test equipment in an air-conditioned room ($20^{\pm 1}$ °C).

A linear cycle with 21 data points on the travel and 4 cycles in each direction gives a total of 164 points.

Guaranteed Specifications

Guaranteed maximum performance values are verified per Newport's A167 metrology test procedure. For more information, please consult the metrology tutorial section in the Newport catalog or at **www.newport.com**

3.2 Mechanical Specifications

		PP	CC	HA
Travel Range (mm)			300; 400; 500 and 600	
MIM (µm)			1.25	0.2
Uni-directional Repeatability (µm)			1.25	0.5
Bidirectional Repeatability (µm)			2.5 or ±1.25	1 or ±0.5
On-Axis Accuracy [1] (µm)	IMS300:		10 or ±5	8 or ±4
	IMS400:		12.5 or ±6.25	11 or ±5.5
	IMS500:		15 or ±7.5	12.5 or ±6.25
	IMS600:		20 or ±10	15 or ±7.5
Maximum Speed (mm/s)		100	200	200
Pitch [1] [2] (µrad)			IMS300: 150 or ±75	
			IMS400: 150 or ±75	
			IMS500: 150 or ±75	
			IMS600: 250 or ±125	
Yaw [1] [2] (µrad)			IMS300: 100 or ±50	
			IMS400: 150 or ±75	
			IMS500: 150 or ±75	
			IMS600: 150 or ±75	
MTBF (h)			20000	

[1] *Shown are peak to peak, guaranteed specifications or ±half the value as sometimes shown. For the definition of typical specifications which are about 2X better than the guaranteed values, visit www.newport.com for the Motion Control Metrology Primer.*

[2] *To obtain arcsec units, divide µrad value by 4.8.*

CAUTION

To reach specifications stated, stages must be fixed on a plane surface with a flatness of 5 µm.

3.3 Load Specification Definitions

Normal Load Capacity (Cz)

Maximum load a stage can move while maintaining specifications.

This value is given with speed and acceleration specified for each stage, and with a load perpendicular to bearings.

	(M-)IMS-PP	(M-)IMS-CC (M-)IMS-CCHA
Specified Speed (mm/s)	100	200
Specified Acceleration (mm/s²)	400	600

Axial Load Capacity (±Cx)

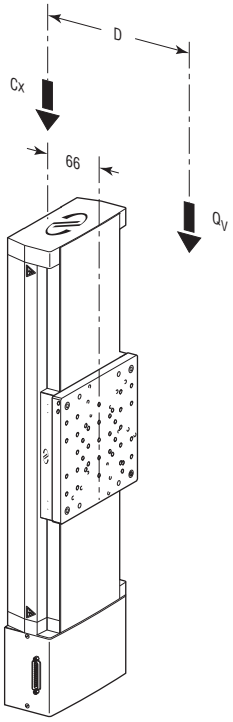
Maximum load along the direction of the drive train.

Off-Centered Load (Q)

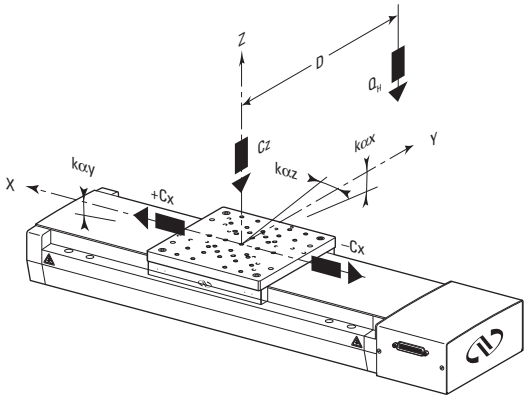
Maximum cantilever-load a stage can move: $Q \leq Cz \div (1 + D/90)$

D: Cantilever distance.

3.4 Load Characteristics and Stiffness



Cz, Normal centered load capacity	600 N
-Cx, +Cx, Axial load capacity	<30 N
kαx, Compliance in roll	1 µrad/Nm
kαy, Compliance in pitch	0.2 µrad/Nm
kαz, Compliance in yaw	1 µrad/Nm
Q, Off-center load	Q_H, $Q_V \leq Cz \div (1 + D/90)$ and Q_V must be $\leq Cx$
D, cantilever distance in mm between the center of the mass of the load and the bearings center.	
Distance between top surface and bearings center	66 mm



3.5 Stage Weights

Weights indicated into the below table are average values for stages with a typical drive unit installed.

	Weight [lb (kg)]
(M-)IMS300	37.4 (17.0)
(M-)IMS400	41.0 (18.7)
(M-)IMS500	45.0 (20.3)
(M-)IMS600	48.4 (22.0)
3-meter MMCABLE-3 Cable	1.54 (0.7)
3-meter MCAB-3 Cable	1.32 (0.6)

The weight variation between drive units is not very significant.

4.0 Drive

4.1 Stepper Drive Version

One stepper-motor configuration is available: (M-)IMS-PP.

This version is equipped with a 4000 pts/rev. rotary encoder located directly on the screw, and is driven in micro-step.

Micro-Step Drive

This is the drive for stepper or pulse-driven motors, transmitted by the electronic unit, which entails a theoretical movement of the motor by one fraction of a full-step. For these translation stages, the micro-step is equivalent to 1/20 of the full-step.

Stepper Motor Performance Specifications

	Resolution (µm)	Speed (mm/s)	Motor
(M-)IMS-PP	1.25	100	UE56UP

4.2 DC-Servo Drive Versions

Two DC-motor configurations are available:

- One version equipped with a 4000 pts/rev. rotary encoder located directly on the screw: (M-)IMS-CC.
- One version equipped with a and linear scale: (M-)IMS-CCHA.

DC-Motor Performance Specifications

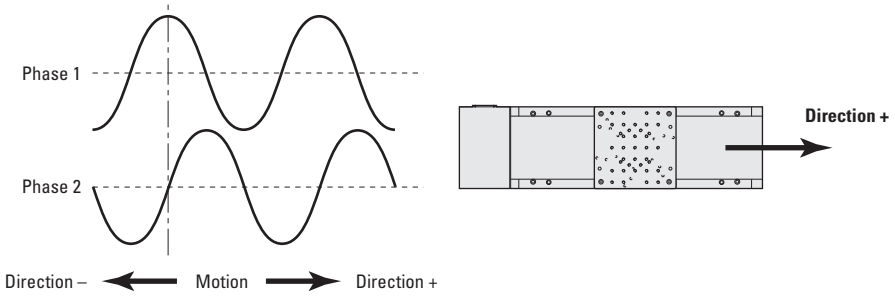
	Resolution (µm)	Speed (mm/s)	Motor
(M-)IMS-CC	1.25	200	UE511S2
(M-)IMS-CCHA	0.1		

5.0 Motor

5.1 UE56UP Motor Characteristics

Motor	Angle by Step (°)	RMS Current per Phase (A)	Resistance (Ω)	Inductance (mH)	Newport Utilization
UE56UP	1.8	2.2	0.77	1.58	Micro-Step

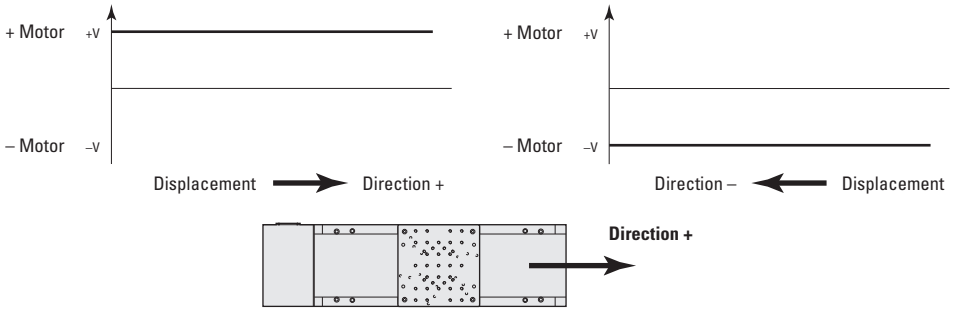
5.2 Command Signals for the Stepper Motor



5.3 UE511S2 Motor Characteristics

Motor	Nominal Voltage (V)	Max. RMS Current (A)	Max. Peak Current (A)	Resistance (Ω)	Inductance (mH)
UE511S2	48	2	4	1.57	1.04

5.4 Command Signals for the DC-Motor

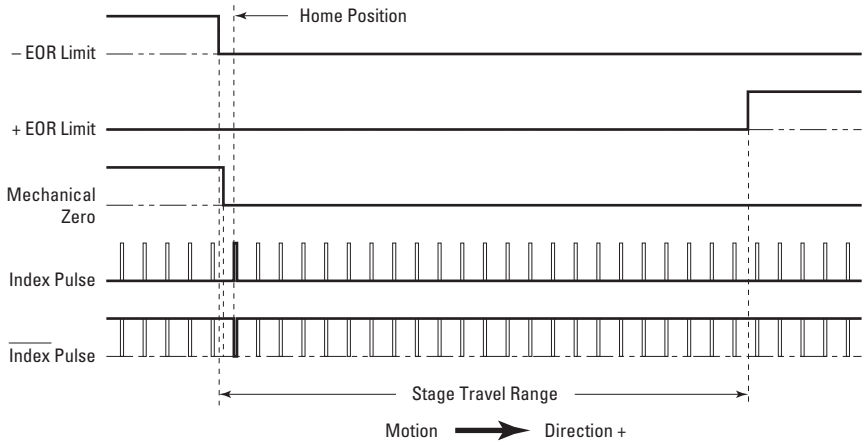


In the above drawings, + Motor signal is referred to – Motor signal.

① When the stage moves in + Direction, the + Motor voltage is higher than – Motor voltage.

② When the stage moves in – Direction, the + Motor voltage is lower than – Motor voltage.

5.5 Sensor Position



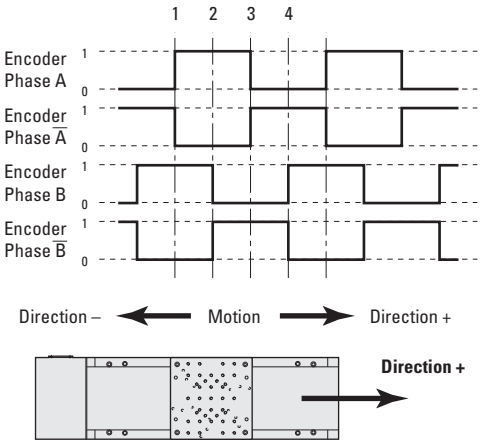
End-of-Run and Mechanical Zero are 5 V open collector type.

The Index Pulse provides a repeatable Home Position at ±1 step.

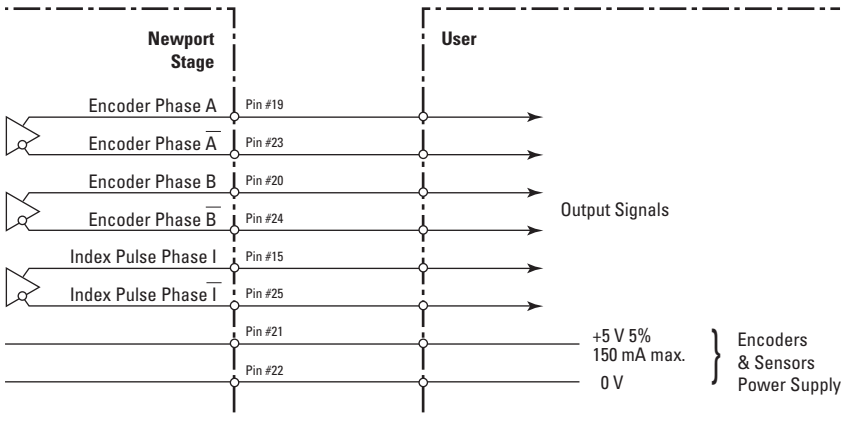
CAUTION

"End-of-Run" and "Mechanical Zero" are active signals and should not be connected to any other source.

5.6 Feedback Signal Position



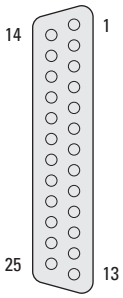
The incremental sensor consists of a optical scale and an encoder head. When the carriages of the stage move, the encoder head generates square signals in quadrature, sent to pins #19, #20, #23 and #24 of the SUB-D25 connector.



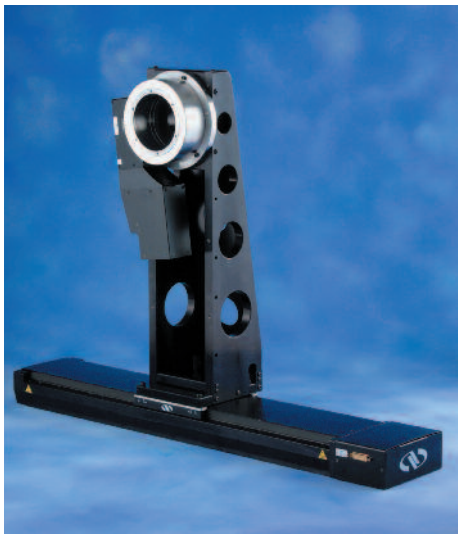
"Encoder" and "Index Pulse" are "differential pair" (type RS-422) type output signals. Using these signals permits a high immunity to noise. Emission circuits generally used by Newport are 26LS31 or MC3487. Reception circuits to use are 26LS32 or MC3486.

5.7 Pinouts

The SUB-D25 connection for the (M-)IMS stages is given in the following table:



	(M-)IMS-PP UE56UP		(M-)IMS-CC & (M-)IMS-CCHA UE511S2
1	Phase 1a	**1**	N.C.
2	N.C.	**2**	N.C.
3	Phase 1b	**3**	N.C.
4	N.C.	**4**	N.C.
5	Phase 2a	**5**	+ Motor
6	N.C.	**6**	+ Motor
7	Phase 1b	**7**	– Motor
8	N.C.	**8**	– Motor
9	N.C.	**9**	N.C.
10	N.C.	**10**	N.C.
11	N.C.	**11**	N.C.
12	N.C.	**12**	N.C.
13	Mechanical Zero	**13**	Mechanical Zero
14	Shield Ground	**14**	Shield Ground
15	Index Pulse I	**15**	Index Pulse I
16	0 V logic	**16**	0 V logic
17	+ End-of-Run	**17**	+ End-of-Run
18	– End-of-Run	**18**	– End-of-Run
19	N.C.	**19**	Encoder Phase A
20	N.C.	**20**	Encoder Phase B
21	N.C.	**21**	Encoder Power: +5 V
22	N.C.	**22**	0 V Encoder
23	N.C.	**23**	Encoder Phase /A
24	N.C.	**24**	Encoder Phase /B
25	Index Pulse /I	**25**	Index Pulse /I



6.0 Connection to Newport Controllers

6.1 Warnings on Controllers

Controllers are intended for use by qualified personnel who recognize shock hazards and are familiar with safety precautions required to avoid possible injury. Read the controller user's manual carefully before operating the instrument and pay attention to all written warnings and cautions.

WARNING

Disconnect the power plug under the following circumstances:

- **If the power cord or any attached cables are frayed or damaged in any way.**
- **If the power plug is damaged in any way.**
- **If the unit is exposed to rain, excessive moisture, or liquids are spilled on the unit.**
- **If the unit has been dropped or the case is damaged.**
- **If you suspect service or repair is required.**
- **Whenever you clean the electronics unit.**

CAUTION

To protect the unit from damage, be sure to:

- **Keep all air vents free of dirt and dust.**
- **Keep all liquids away from the unit.**
- **Do not expose the unit to excessive moisture (85% humidity).**
- **Read this manual before using the unit for the first time.**

WARNING

All attachment plug receptacles in the vicinity of this unit are to be of the grounding type and properly polarized.

Contact your electrician to check your receptacles.

WARNING

This product is equipped with a 3-wire grounding type plug.

Any interruption of the grounding connection can create an electric shock hazard.

If you are unable to insert the plug into your wall plug receptacle, contact your electrician to perform the necessary alterations to ensure that the green (green-yellow) wire is attached to earth ground.

WARNING

This product operates with voltages that can be lethal.

Pushing objects of any kind into cabinet slots or holes, or spilling any liquid on the product, may touch hazardous voltage points or short out parts.

6.2 Connection

On each stage is represented a label which indicates its name and its serial number.

WARNING

Always turn the controller's power OFF before connecting to a stage.

Stages may be connected to the rear panel motor connectors any time prior to power-up with the supplied cable assemblies.

NOTE

These stages are ESP compatible. Enhanced System Performance is Newport's exclusive technology that enables Newport ESP motion controllers to recognize the connected Newport ESP stage and upload the stage parameters. This ensures that the user can operate the motion system quickly and safely.

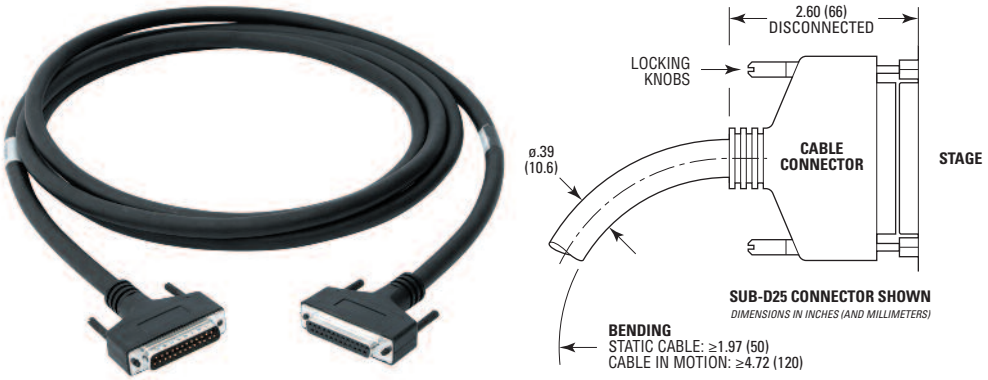
6.3 Cables

Our stages are delivered with a **MMCABLE-3** or **MCAB-3** 3-meter cable according to the (M-)IMS stage you bought. This cable is equipped with a SUB-D25M connector so it can be directly connected to our controllers/drivers.

The cable supplied with your (M-)IMS stage is given in the following table:

Stages	Supplied Cable
(M-)IMS-PP	MMCABLE-3
(M-)IMS-CC (M-)IMS-CCHA	MCAB-3

6.4 MMCABLE-3 Cable



WARNING

This cable is shielded correctly. For a correct operation, make sure to lock connectors (ground continuity provided by the cable).

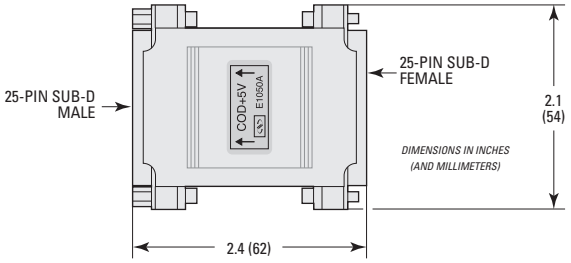
For applications where the standard 3-meter cable (**MMCABLE-3**) included with your rotation stage is not adequate, Newport offers longer length cables designed to ensure the integrity of your positioning application.

These cables are specially shielded and terminated with Newport's standard SUB-D25 connectors. They are available in 5-m (**MMCABLE-5**), 7-m (**MMCABLE-7**) or 10-m (**MMCABLE-10**) lengths.

WARNING

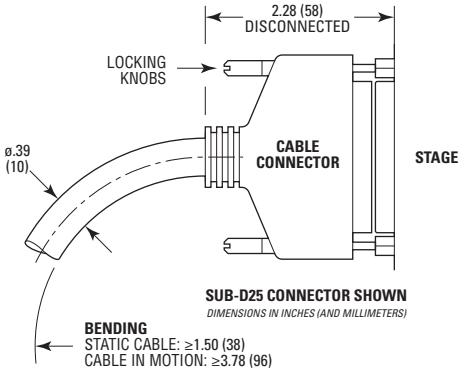
Keep the motor cables at a safe distance from other electrical cables in your environment to avoid potential cross talk.

For cable lengths in excess of 3 meters, we recommend the **MMCABLE-REG** to ensure a high quality, regulated 5 V supply to the rotation stages.



This regulator is available as an option. Please note that for best efficiency, this regulator should be attached to the stage to re-adjust the 5 V coming from the controller through the long cable.

6.5 MCAB-3 Cable



WARNING

This cable is shielded correctly. For a correct operation, make sure to lock connectors (ground continuity provided by the cable).

For applications where the standard 3-meter cable (**MCAB-3**) included with your stage is not adequate, Newport offers longer length cables designed to ensure the integrity of your positioning application.

These cables are specially shielded and terminated with Newport's standard SUB-D25 connectors. They are available in 5-m (**MCAB-5**), 7-m (**MCAB-7**) or 10-m (**MCAB-10**) lengths.

WARNING

Keep the motor cables at a safe distance from other electrical cables in your environment to avoid potential cross talk.

7.0 Connection to Non-Newport Electronics

7.1 Connections

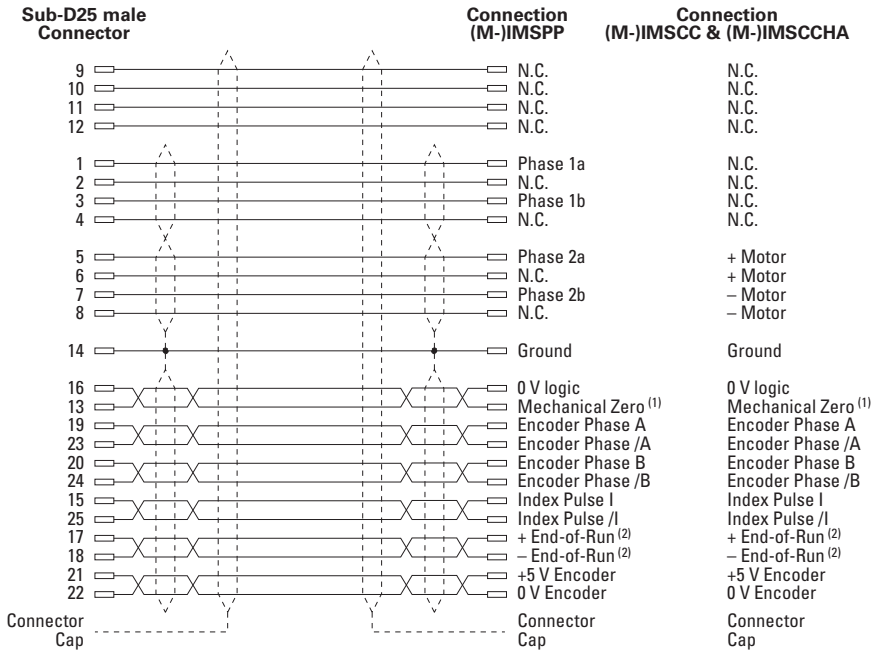
WARNING

Newport is not responsible for malfunction or damage to a (M-)IMS stage when it is used with non- Newport controllers.

WARNING

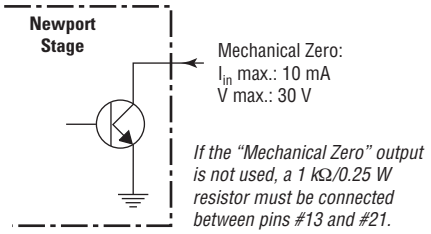
Newport guarantees "CE" compliance of the (M-)IMS stages only if they are used with Newport cables and controllers.

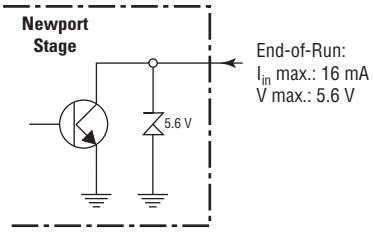
Nevertheless, the figure below shows the wiring when a (M-)IMS stage is used with non-Newport controllers.


Sub-D25 male Connector
Connection (M-)IMSPP
Connection (M-)IMSCC & (M-)IMSCCHA
9 N.C. N.C.
10 N.C. N.C.
11 N.C. N.C.
12 N.C. N.C.
1 Phase 1a N.C.
2 N.C. N.C.
3 Phase 1b N.C.
4 N.C. N.C.
5 Phase 2a + Motor
6 N.C. + Motor
7 Phase 2b – Motor
8 N.C. – Motor
14 Ground Ground
16 0 V logic 0 V logic
13 Mechanical Zero (1) Mechanical Zero (1)
19 Encoder Phase A Encoder Phase A
23 Encoder Phase /A Encoder Phase /A
20 Encoder Phase B Encoder Phase B
24 Encoder Phase /B Encoder Phase /B
15 Index Pulse I Index Pulse I
25 Index Pulse /I Index Pulse /I
17 + End-of-Run (2) + End-of-Run (2)
18 – End-of-Run (2) – End-of-Run (2)
21 +5 V Encoder +5 V Encoder
22 0 V Encoder 0 V Encoder
Connector Cap
Connector Cap
Connector Cap

(1) The Mechanical Zero logic signal is open collector type. It supports until 30 V and 10 mA.

(2) Open collector type with a 5.6 V protective Zener diode.

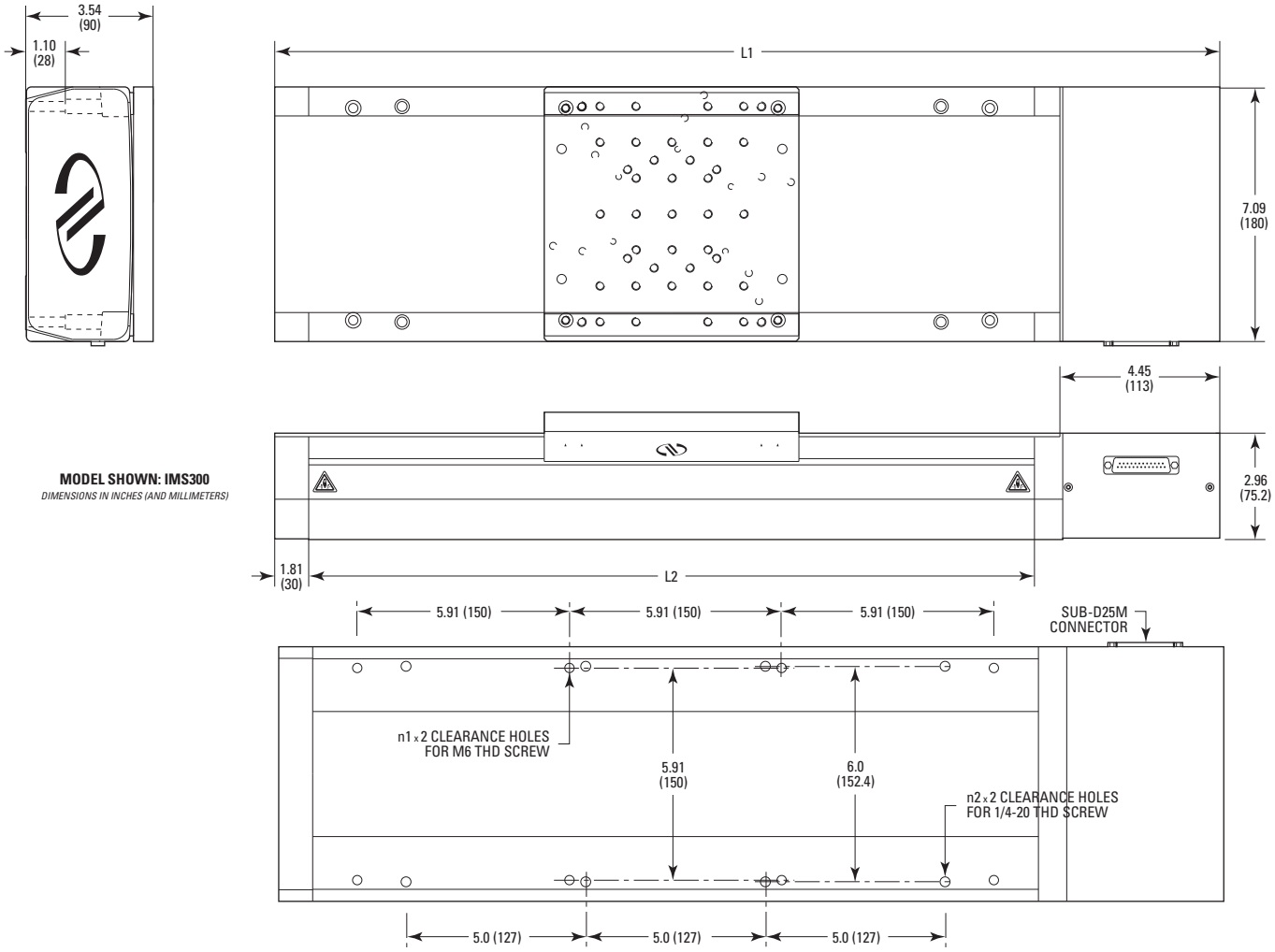

Newport Stage
Mechanical Zero:
I_{in} max.: 10 mA
V max.: 30 V
If the "Mechanical Zero" output is not used, a 1 kΩ/0.25 W resistor must be connected between pins #13 and #21.



"Encoder" and "Index Pulse" are "differential pair" (type RS-422) type output signals. Using these signals permits a high immunity to noise. Emission circuits generally used by Newport are 26LS31 or MC3487. Reception circuits to use are 26LS32 or MC3486.

8.0 Dimensions

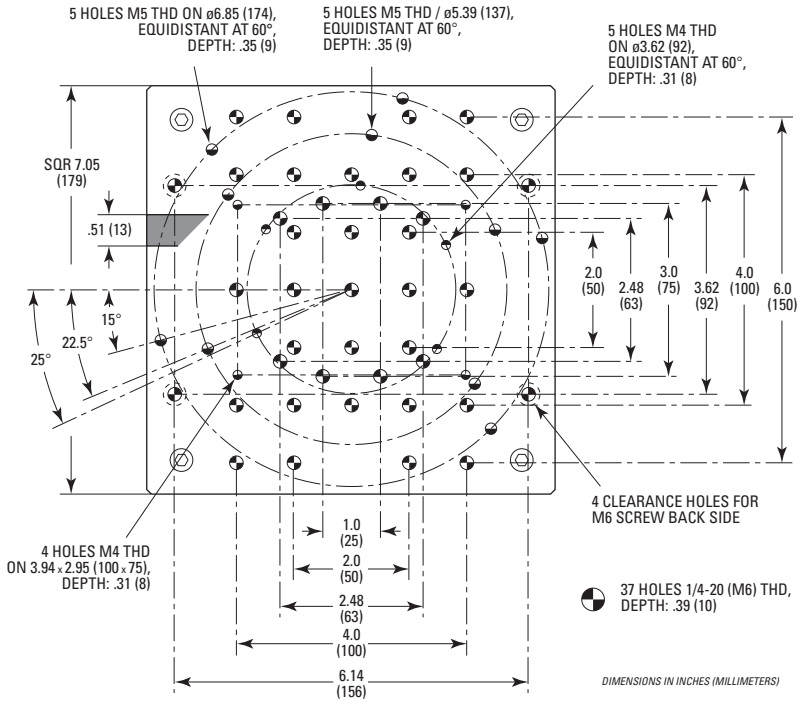
8.1 (M-)IMS Stages



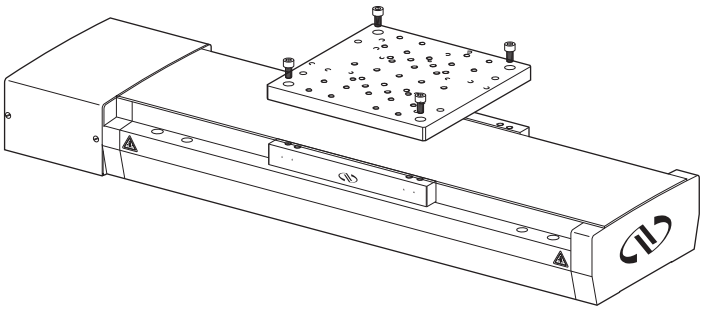
MODEL SHOWN: IMS300
DIMENSIONS IN INCHES (AND MILLIMETERS)

MODEL (METRIC)	n1	n2	TRAVEL	L1	L2
(M-)IMS300	4	4	11.81 (300)	26.30 (668)	20.20 (513)
(M-)IMS400	4	4	15.75 (400)	30.24 (768)	24.13 (613)
(M-)IMS500	4	6	19.69 (500)	34.17 (868)	28.07 (713)
(M-)IMS600	6	6	23.62 (600)	38.11 (968)	32.01 (813)

8.2 (M-)IMS Stages Top Plate Interface

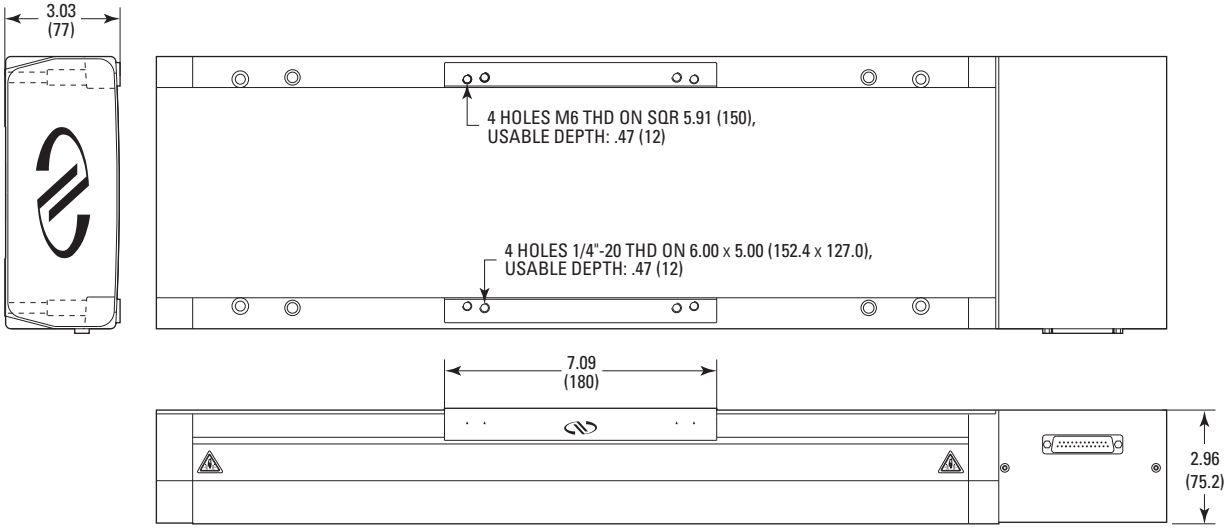

5 HOLES M5 THD ON ø6.85 (174), EQUIDISTANT AT 60°, DEPTH: .35 (9)
5 HOLES M5 THD / ø5.39 (137), EQUIDISTANT AT 60°, DEPTH: .35 (9)
5 HOLES M4 THD ON ø3.62 (92), EQUIDISTANT AT 60°, DEPTH: .31 (8)
SQR 7.05 (179)
.51 (13)
15°
22.5°
25°
2.0 (50)
2.48 (63)
3.0 (75)
3.62 (92)
4.0 (100)
6.0 (150)
4 CLEARANCE HOLES FOR M6 SCREW BACK SIDE
4 HOLES M4 THD ON 3.94 x 2.95 (100 x 75), DEPTH: .31 (8)
1.0 (25)
2.0 (50)
2.48 (63)
4.0 (100)
6.14 (156)
37 HOLES 1/4-20 (M6) THD, DEPTH: .39 (10)
DIMENSIONS IN INCHES (MILLIMETERS)

8.3 (M-)IMS Stages without Top Plate Interface



Sometimes, it is necessary to remove the top plate interface of a (M-)IMS stage (to make an XY assembly, for example).

To do that, just unscrew the 4 CHc M6 x 0.63 (16) on sqr 5.91 (150) screws at the 4 corners of the plate with the wrench supplied with the stage. Both IMS and M-IMS stages will then have the same following interfaces:

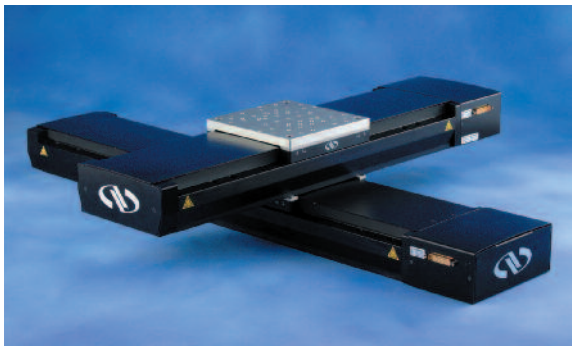


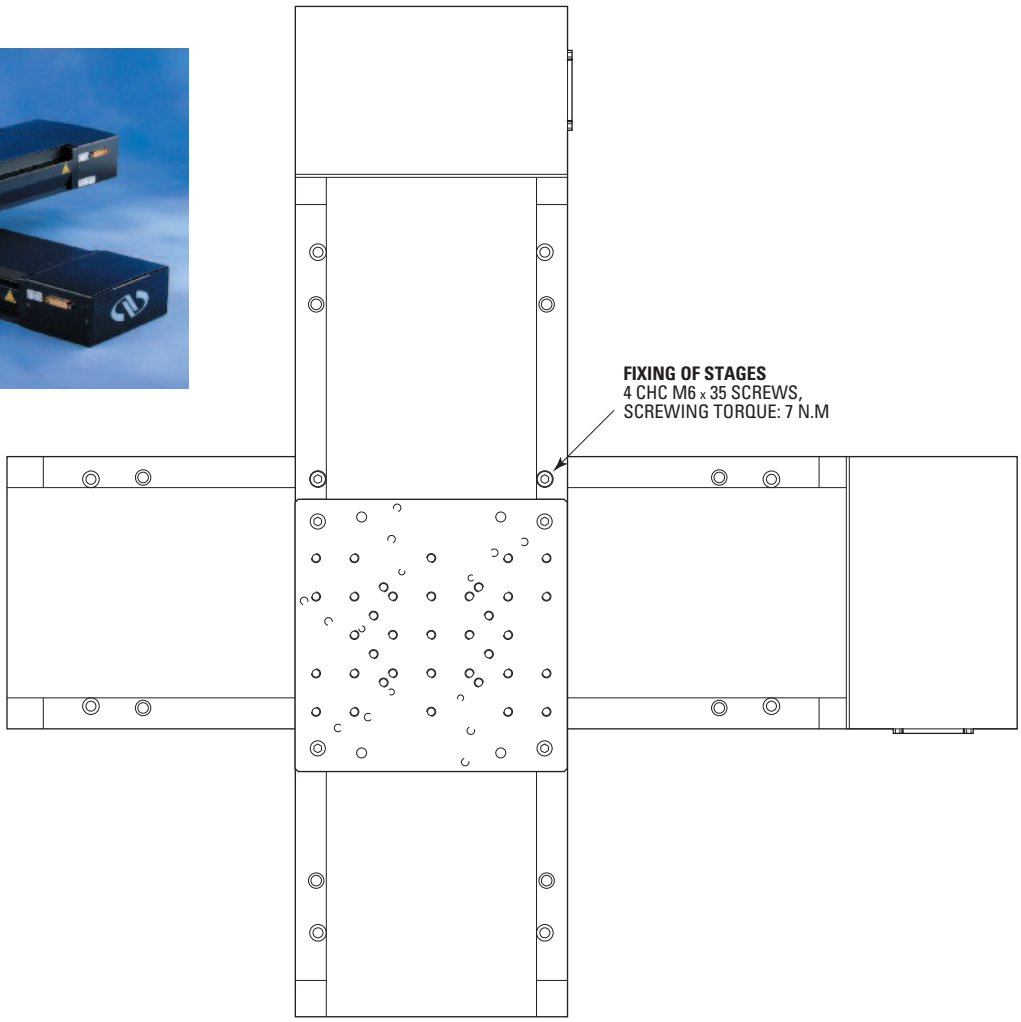
9.0 XY Assemblies

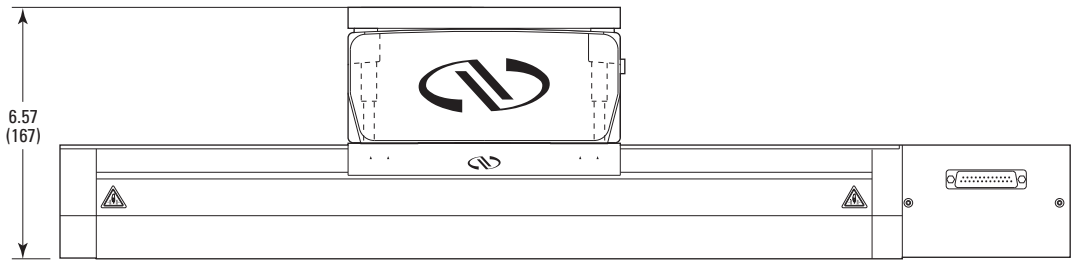
ATTENTION

All configurations of XY travel ranges are possible. However, it is recommended to place the IMS stage with the longer travel range at the bottom.

The maximum travel range of the top level IMS stage depends on the cantilever load and dynamic specifications to reach.

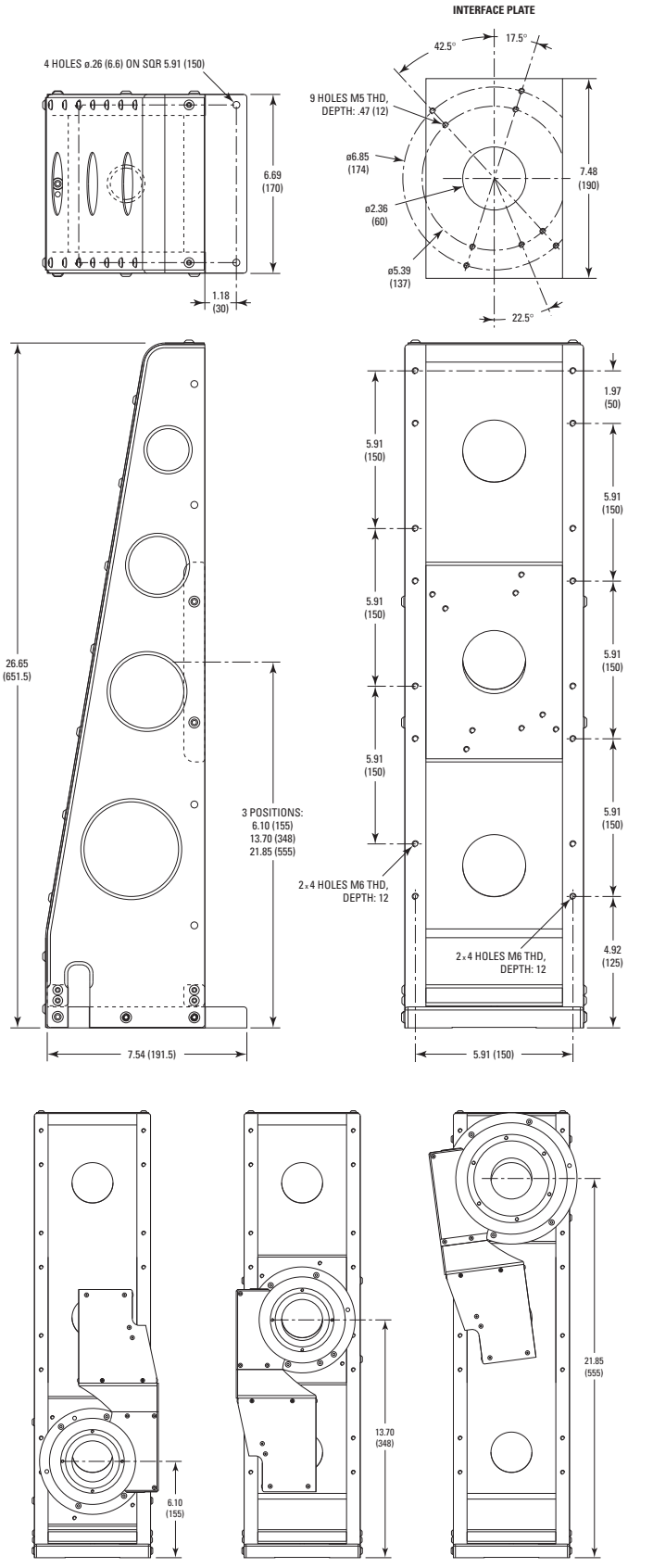


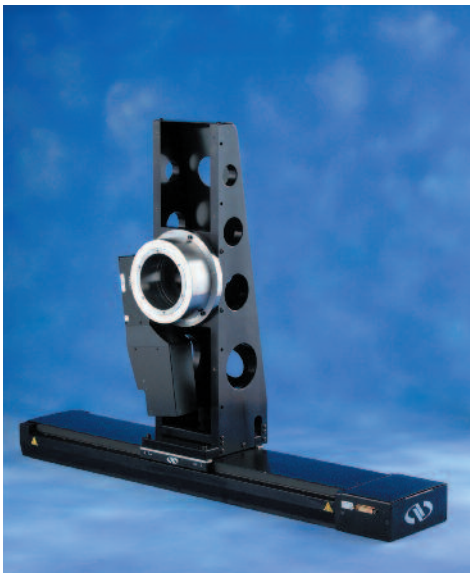




10.0 Accessory: EQ180 Bracket

Newport's EQ180 bracket (to order separately) is ideal for mounting our IMS Series of linear stages and RV120 or RV160 rotation stages for stable and stiff muti-axis positioning systems.





Interface plate position of the EQ180 bracket.

11.0 Maintenance

RECOMMENDATION

It is recommended to contact our After Sales Service which will know to define the appropriate maintenance for your application.

11.1 Maintenance

The ILS stage requires no particular maintenance. Nevertheless, this is a precision mechanical device that must be kept and operated with caution.

PRECAUTIONS

The ILS stage must be used or stocked in a clean environment, without dust, humidity, solvents or other substances.

RECOMMENDATION

It is recommended to return your ILS stage to Newport's After Sales Service after every 2000 hours of use for lubrication.

If your stage is mounted on a workstation and cannot be easily removed, please contact Newport's After Sales Service for further instructions.

11.2 Repair

CAUTION

Never attempt to disassemble a component of the stage that has not been covered in this manual.

To disassemble a non specified component can cause a malfunction of the stage.

If you observe a malfunction in your stage, please contact us immediately to arrange for a repair.

CAUTION

Any attempt to disassemble or repair a stage without prior authorization will void your warranty.

11.3 Calibration

CAUTION

It is recommended to return your ILS stage to Newport once a year for recalibration to its original specifications.

Service Form

Your Local Representative
Tel.: _____
Fax: _____

Name: _____ Return authorization #: _____
(Please obtain prior to return of item)

Company: _____

Address: _____ Date: _____

Country: _____ Phone Number: _____

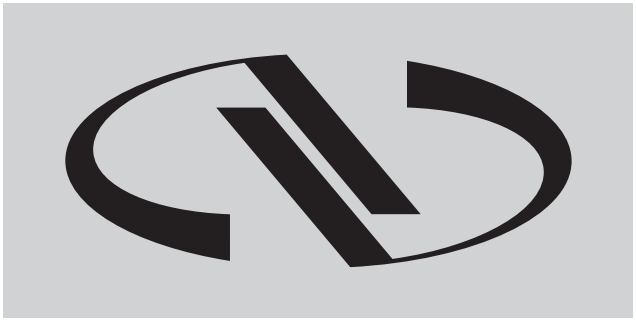
P.O. Number: _____ Fax Number: _____

Item(s) Being Returned:

Model #: _____ Serial #: _____

Description: _____

Reasons of return of goods (please list any specific problems): _____



Newport®

Experience | Solutions

Visit Newport Online at:
www.newport.com

North America & Asia

Newport Corporation

1791 Deere Ave.
Irvine, CA 92606, USA

Sales

Tel.: (800) 222-6440

e-mail: sales@newport.com

Technical Support

Tel.: (800) 222-6440

e-mail: tech@newport.com

Service, RMAs & Returns

Tel.: (800) 222-6440

e-mail: service@newport.com

Europe

MICRO-CONTROLE Spectra-Physics S.A.S

9, rue du Bois Sauvage
91055 Évry CEDEX
France

Sales & Technical Support

Tel.: +33 (0)1.60.91.68.68

e-mail: france@newport.com

Service & Returns

Tel.: +33 (0)2.38.40.51.55